# Low-cost Platform Technology for **LWIR Sensor Arrays**

for Use in Automotive Night Vision and Other **Applications** 

I. Herrmann; M. Hattaß; D. Oshinubi; T. Pirk; C. Rettig; K.-F. Reinhart; E. Sommer

Robert Bosch GmbH, Corporate Sector Research and Advance Engineering Microsystem Technologies, P.O Box 10 60 50, 70049 Stuttgart, GERMANY







## Contents

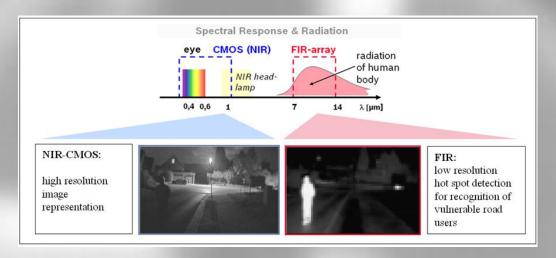
- Introduction:
   Multi-spectral Approach to Automotive Night-vision
- → ADOSE
- Low-end Requirements
- How to Do "Low-cost"
- ADOSE Achievements
- Ascend From Low-end
- → RTFIR
- Conclusion and Outlook







## Multi-spectral Approach to Automotive Night-Vision



- NIR-CMOS imager presents a natural and high-quality view to user
- FIR imager gives temperature information
- NIR allows state-of-the art detection of road-signs, lane boundaries etc.
- FIR allows differentiation of "dead" and "living"
- Data fusion of NIR and FIR allows high alarm rates with low false positives







## **ADOSE**

The research leading to these results has received funding from the European Community's Seventh Framework Programme (FP7/2007-2011) under grant agreement n° 216049 - ADOSE Project."





ADOSE Project no. 216049:
Reliable Application Specific Detection of Road Users
with Vehicle On-Board Sensors

ADOSE Website: http://www.adose-eu.org







## Low-end Requirements



#### **Example Scenario:**

- Extra-urban
- Single-lane road (i.e. no Autobahn)
- $\rightarrow$   $v_{max} = 100 \text{ km/h}$
- Detection distance 120m
- Minimum hot-spot size for a human 1 x 5 (hor. X vert.)
- → Thermal resolution 0.5 K

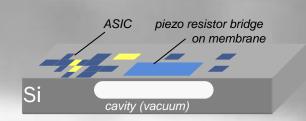
FIR camera requirements		Remark	
Hor. Field of View (FOV):	± 12°	For data fusion with NIR	
Angular Resolution:	4,18 pixel / $^{\circ}$	Defined by smallest object to be resolved @ 120m	
<b>Object Temperature resolution:</b>	< 500 mK	for hot-spot detection; no image display; NETD<300mK for chip @F#1 optics	
Frame Response:	> 12,5 Hz	for 3 verifications of object in the NIR image	
Array Size:	100 x 50 pixels	Defined by FOV and angular resolution	
Wavelength Range:	7-14 µm	Spectral emission maximum of vulnerable road users	



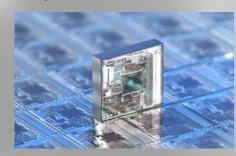


## How to Do "Low-cost"

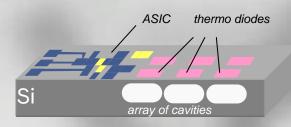
Take a well-established, high volume MEMS-process ...



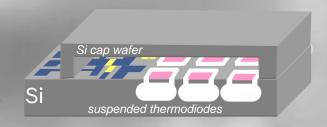
Pressure sensor



... and use it for a completely different type of sensor



Far-infrared-array







## **ADOSE Achievements**

- Proof-of-concept demonstrator finished
  - 42 x 28 pixels
  - 5 Hz
  - .5 K NETD@F#1
- First ADOSE silicon ready
  - 100 x 50 pixels
  - 12.5 Hz thermally, 25 Hz read-out
  - .3 K NETD@F#1 (target)
- Transfer to Bosch MEMS facility started
- Chip-on-board assembly verified (with FhG IZM, Berlin)
- Demonstrator boards, housing and optics ready (with FhG IZM, UMICORE)













## Ascend From Low-end (RTFIR development goals)

Shrink down the pixel structure

distribution, as well as in the event of applications for industrial property rights.

- Use the capabilities of more recent CMOS for more ROIC functionality
- Implement a new low-noise read-out concept
- Utilize a new wafer-level encapsulation technology to reduce chip cost
- Improve the absorption
- Develop a new low-cost FIR-optics process (@ FhG IWM)

	ADOSE	RTFIR
Pixel Pitch [µm]	100	28
Absorber area [µm²]	4700	345
Fill factor [%]	47	44







CR/ARY3-He | 17/05/2011 | © Robert Bosch GmbH 2011. All rights reserved, also regarding any disposal, exploitation, reproduction, editing

## RTFIR











"Thin Un-cooled (RT) FIR-Imager With Nano-scaled Absorption Layers"











## **Conclusion and Outlook**

- Concept for low-cost, low-end FIR imager was proven
- → 1<sup>st</sup> gen. BOSCH low-cost FIR chip (100x50) in transfer to fab
- → Low-cost platform development for 2<sup>nd</sup> gen. (QVGA+) started
- Next steps:
  - Pixel shrink
  - New ASIC
  - New wafer-level encapsulation
  - Low-cost optics



